

PETER F. GIRARD
8001 VISTA DRIVE
LA MESA, CALIFORNIA 91941

TITLE OF THE INVENTION

EPICYCLIC CROSS PISTON INTERNAL COMBUSTION ENGINE

BACKGROUND OF THE INVENTION

The invention relates to an internal combustion engine and more specifically to one incorporating epicyclic sets of cross pistons.

It is a well known fact that a point on a circle rolling around the inside of another circle of twice its diameter, without slippage, will travel forward and backward along a straight line; a diameter of the larger circle.

Piston designers of the past have often been intrigued with this relationship and some have attempted to utilize it in attempts to approve the design of engines as it holds the promise of simplifying the piston/connecting-rod/crankshaft relationship. Engines employing conventional gears to achieve this action have been constructed, but none have been produced in quantity, due apparently to problems involving the gearing.

Some prior art internal combustion engines will be discussed below.

The Llewellyn U.S. patent 3,329,134 is directed to a small sized gasoline powered engine. The objects of the invention are to provide an engine with a greatly reduced number of working parts, to provide an arrangement of the parts which will simplify and compact the engine so that it is especially suitable for use on power mowers, chain saws and the like and to reduce the

1 torsion imposed upon the crankshaft and the stress placed on other engine parts to a point where
2 lightweight and relatively inexpensive components may be used. The crankshaft is journaled in
3 the pistons rather than in the crankcase as in a conventional engine. This eliminates the use of
4 connecting rods and results in an unusual crankshaft motion from which mechanical advantage is
5 derived.

6 The Paillier US patent 3,946,706 is directed to a rotary engine comprising four cylinders
7 in a star cluster. It has a first assembly of two pistons suitable to slide in two of the cylinders
8 connected together head to tail by a first rigid cross piece. It also has a second assembly of two
9 pistons suitable to slide in the other two cylinders and connected together head to tail by a second
10 rigid cross piece. It also has a mechanism with eccentrics suitable to transform the alternating
11 sliding of these two assemblies into rotation of the shaft.

12 The Wrin US patent 4,026,252 is directed to a two-cycle engine having a pair of pistons
13 mounted within a pair of cylinders which are arranged in an oppositely facing in-line manner. It
14 has separate connecting rods for each of the pistons that are mounted on a crankshaft that is
15 rotatably mounted with respect to a planetary gear carrier.

16 The Stiller et al US patent 5,046,459 is directed to an engine having two pairs of pistons
17 each pair are connected to each other by a rigid connecting rod. A trammel gear is connected to a
18 first connecting rod through a first pivot pin. The trammel gear is also connected to a second
19 connecting rod through a second pivot pin. By movement of the various pistons in a
20 predetermined sequence, the trammel gear will be caused to rotate and thereby convert the
21 transnational movement of the connecting rods into responsive rotary and translator movement of

1 the trammel gear.

2 The Puzio US patent 5,228,416 is directed to an internal combustion engine utilizing a
3 disc-shaped crankshaft operatively connected with respect to at least one pair of opposed
4 pistons. Each piston of each pair is fixedly secured with respect to a shaft extending
5 therebetween. With two pairs of pistons they are arranged at right angles with respect to one
6 another such that each piston fires controlled by a timing device to maintain the rotary
7 crankshaft. The crankshaft can include a gear device or a friction surface device about the
8 external periphery thereof to facilitate distribution of power therefrom. The crankshaft defines
9 an aperture therein within which a crankpin is positioned with an off set connecting arm
10 extending in each opposite direction. The offset connecting arm extends into a bore within
11 which is positioned the rod extending to each pair of pistons. The path of movement of the
12 crankpin is circular to receive driving force of the pistons at selectively timed intervals.

13 The Bracket US patent 5,259,256 is directed to a device for translating rotary to linear
14 motion and vice-versa and it includes a reciprocating linearly moving shuttle with a central
15 aperture. The aperture has a pair of opposing gear racks protruding towards the center which
16 capture therebetween a pair of pinion sectors rotatably mounted to the crankpin of a rotatable
17 crankshaft with the axis of the crankshaft rotation perpendicular to the linear path of the shuttle.
18 The pinon sectors are free to rotate about the crankpin and articulate independently of each other
19 through a selected angular range.

20 The Vaux et al US patent 5,331,926 is directed to an internal combustion engine utilizing
21 a dwelling scotch yoke and a journaled flywheel and a unique combination for stalling the

1 translator movement of an oppositely paired pistons during the detonation of the fuel mixture
2 to achieve a clear exhaust and an energy efficient engine.

4 SUMMARY OF THE INVENTION

5 It is a well known fact that a point on a circle rolling around the inside of another circle of
6 twice its diameter, without slippage, will travel forward and backward along a straight line that is
7 also the diameter of the larger circle. This principal has been utilized in the epicyclic cross
8 piston internal combustion engine that has been designed.

9 The salient features of the system described herein are as follows:

10 1) it has a reciprocating engine (Otto or Diesel cycle) employing essentially conventional
11 cylindrical pistons and utilizing the above noted epicyclic principle without recourse to the use of
12 gears, cams, link belts or other type of belts in the main drive train. The engine may utilize four,
13 six or more cylinders.

14 2) transmission of power to the output shaft is by means of a very short crankshaft
15 incorporating, in the case of a four cylinder engine, a single throw. The cylinders are not
16 arranged radially around a single throw crankshaft in the manner of a conventional aircraft radial
17 engine.

18 3) because of the epicyclic features, conventional piston/crankshaft connecting rods with
19 wrist pins are not required; the connecting rods are rigidly attached to the pistons.

20 4) cylinders are nested in such a manner that a four cylinder engine would only be
21 approximately 1/3 the length of a conventional in-line engine.

6 7) the engine would usually be somewhat lighter than a conventional engine of
7 comparable power.

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Figure 1 is a schematic perspective view illustrating how the axial travel of the pistons is transmitted into a rotational movement for the output shaft;

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Figure 3 is a cross sectional view taken along lines 3-3 of Figure 2;

Figure 4 is a schematic top plan view of the four cycle epicyclic cross piston engine;

Figure 5 is a schematic horizontal cross sectional view of a two cycle epicyclic cross piston engine;

Figure 6 is a cross sectional view taken along lines 6-5 of Figure 5; and

Figure 7 is a schematic top plan view of the two cycle epicyclic cross piston engine.

DESCRIPTION OF THE PREFERRED EMBODIMENT

The epicyclic cross piston engine will now be described by referring to Figures 1-7 of the drawings. Figure 1 is a schematic front perspective view that clearly explains the basic principles of the engine. A piston 10 and a piston 12 are rigidly connected to the opposite ends of a master connecting rod 14. The master connecting rod has a longitudinally extending Y-axis. The respective pistons would move upwardly and downwardly in their own separate cylinders (not shown). Another pair of pistons 15 and 16 are rigidly connected to the opposite ends of secondary connecting rod 18. Secondary connecting rod 18 has a longitudinally extending X-axis that is laterally offset from the Y-axis. A vertical plane passing through the Y-axis and horizontal plane passing through the X-axis would intersect each other at a ninety degree angle. Pistons 15 and 16 would travel reciprocally back and forth in their own separate cylinders (not shown). The reciprocal motion of the respective connecting rods produces a rotational motion of the output shaft 20 that has a Z-axis that is perpendicular to the X-axis and the Y-axis.

A bellcrank coordinating arm 22 has a pin 23 rigidly secured thereto and it has an axial

1 A-axis that is parallel to the Z-axis. Pin 23 is journaled in a bore hole passing transversely
2 through the midpoint of connecting rod 18. A pin 24 has an axial B-axis that is parallel to the
3 A-axis and they are separated by a distance E. One end of pin 24 is rigidly secured to bellcrank
4 coordinating arm 22 and its opposite end is rigidly connected to bellcrank output arm 26. Pin 24
5 is journaled in the midpoint position of connecting rod 14. A pin 28 has an axial C-axis whose
6 one end is journaled in a bore hole in bellcrank output arm 26. The other end of pin 28 is rigidly
7 secured to driveshaft link 29. The C-axis and B-axis are parallel to each other and they are
8 spaced apart a distance F. Output shaft 20 has its rear end rigidly secured to driveline 29. The
9 distance F is equal to $\frac{1}{2}$ E. When combustion takes place in its proper sequence in the respective
10 cylinders, connecting rod 18 will travel horizontally along the X-axis and connecting rod 14 will
11 travel vertically along the Y-axis and the combination of these two motions will produce a
12 rotational travel output on the output shaft 20 that has a Z-axis.

13 A four cylinder epicyclic cross piston engine is illustrated in Figures 2-4. The engine is
14 generally designated numeral 32. It has four cylinders, 34a, 34b, 34c, and 34d whose bottom
15 ends are each secured in a crankcase 35. Each cylinder has a cylinder head 36 and a sparkplug 37
16 that extends into the compression chamber 38. An intake valve 39 and an exhaust valve 40 are
17 reciprocally mounted in cylinder head 36. The respective valves are opened and closed by valve
18 rocker arms 41 that are pushed upwardly by push rods 42 that are lifted upwardly by valve cams
19 44 as they rotate. The push rods 42 are surrounded by a housing 45. Lubrication is provided to
20 the rocker arms by rocker arm lubrication tube 47 that is connected to oil pump 48.

21 The rear end of pistons 50a and 50c are rigidly connected to the opposite ends of master

1 connecting rod 52. The rear ends of cylinders 50b and 50d are rigidly connected to the opposite
2 ends of secondary connecting rod 53. The respective cylinders are surrounded by a coolant
3 jacket 55. Lateral movement of the respective connecting rods as they travel through their
4 reciprocal motion is stabilized by connecting rod lateral support slippers 57.

5 Fuel is supplied to the respective cylinders by a distributor 59 through the intake manifold
6 60. An exhaust manifold 61 is connected to each of the exhaust valves 40. Ignition is provided
7 to each combustion chamber 38 by a distributor 63. Oil tank 65 is connected to an oil scavenging
8 pickup 66 and also to the oil return line 67 that connects to oil pump 48.

9 Looking to Figure 2, cylinder 50d is shown removed for clarity. The X-axis of secondary
10 connecting rod 53 is shown laterally spaced behind master connecting rod 52 by a distance J.
11 The rear end of pin 70 is journaled in a bore hole in secondary connecting rod 53. The front end
12 of pin 70 is rigidly secured to the bottom end of bellcrank coordinating arm 72 and pin 70 has an
13 A-axis. A pin 73 having a B-axis has its rear end rigidly secured to the top end of bellcrank
14 coordinating arm 72. The intermediate portion of pin 73 is journaled in a bore hole in master
15 connecting rod 52. The distance between A-axis and B-axis is E. A bellcrank output arm 75 has
16 its top end rigidly secured to the front end of pin 73. The bottom end of bellcrank output arm 75
17 has a pin 76 rigidly secured thereto and it has a C-axis. The distance between C-axis and B-axis
18 is a distance F and F is equal to $\frac{1}{2}$ E. The front end of pin 76 is journaled in a bore hole in drive
19 shaft link 77. Drive shaft link 77 is rigidly secured to the rear end of output shaft 79 which has a
20 Z-axis. A flywheel 80 would be secured forwardly on output shaft 79.

21 During operation, points H and G are restrained to travel only along the X-axis and the Y-

axis respectfully by the rigid nature of the connecting rods joining them. Their action is coordinated by bellcrank coordinating arm 72 and in so doing, point K travels in a circular path around the Z-axis when the distance F on the driveshaft link 77 is one half of the distance E on the bellcrank coordinating arm 72.

A two cycle epicyclic cross piston engine is illustrated in figures 5-7. The engine is generally designated numeral 82. Similar structure in the two cycle engine 82 is given the same identification numbers as those set forth in the four cycle epicyclic cross piston engine 32.

Two cycle engine 82 has four cylinders, 34a, 34b, 34c, and 34d whose bottom ends are each secured in a crankcase 35. Each cylinder has a cylinder head 36 and a sparkplug 37 that extends into the compression chamber 38.

The rear end of pistons 50a and 50c are rigidly connected to the opposite ends of master connecting rod 52. The rear ends of cylinders 50b and 50d are rigidly connected to the opposite ends of secondary connecting rod 53. The respective cylinders are surrounded by a coolant jacket 55. Lateral movement of the respective connecting rods as they travel through their reciprocal motion is stabilized by connecting rod lateral support slippers 57.

Fuel is supplied to the respective cylinders by a distributor 59 through the intake manifold. An exhaust manifold is connected to each of the exhaust valves. Ignition is provided to each combustion chamber 38 by a distributor.

Looking to Figure 5, cylinder 50d is shown removed for clarity. The X-axis of secondary connecting rod 53 is shown laterally spaced behind master connecting rod 52 by a distance J. The rear end of pin 70 is journaled in a bore hole in secondary connecting rod 53. The front end

1 of pin 70 is rigidly secured to the bottom end of bellcrank coordinating arm 72 and pin 70 has an
2 A-axis. A pin 73 having a B-axis has its rear end rigidly secured to the top end of bellcrank
3 coordinating arm 72. The intermediate portion of pin 73 is journaled in a bore hole in master
4 connecting rod 52. The distance between A-axis and B-axis is E. A bellcrank output arm 75 has
5 its top end rigidly secured to the front end of pin 73. The bottom end of bellcrank output arm 75
6 has a pin 76 rigidly secured thereto and it has a C-axis. The distance between C-axis and B-axis
7 is a distance F and F is equal to $\frac{1}{2}$ E. The front end of pin 76 is journaled in a bore hole in drive
8 shaft link 77. Drive shaft link 77 is rigidly secured to the rear end of output shaft 79 which has a
9 Z-axis. A flywheel 80 would be secured forwardly on output shaft 79.